Solutions to Assignments 02

1. Geodesics

(a) With the Lagrangian

$$\mathcal{L}(x^{\mu}, \dot{x}^{\mu}) = \frac{1}{2} g_{\mu\nu} \frac{dx^{\mu}}{d\tau} \frac{dx^{\nu}}{d\tau} = \frac{1}{2} g_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu}$$
(1)

where $g_{\mu\nu} = g_{\mu\nu}(x^{\rho})$ one computes

$$\frac{\partial \mathcal{L}}{\partial x^{\mu}} = \frac{1}{2} \dot{x}^{\rho} \dot{x}^{\nu} \partial_{\mu} g_{\rho\nu}$$
⁽²⁾

$$\frac{\partial \mathcal{L}}{\partial \dot{x}^{\mu}} = g_{\rho\nu} \dot{x}^{\rho} \frac{\partial}{\partial \dot{x}^{\mu}} \dot{x}^{\nu} = g_{\rho\nu} \dot{x}^{\rho} \delta^{\nu}_{\mu} = g_{\rho\mu} \dot{x}^{\rho}$$
(3)

$$\frac{d}{d\tau} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}^{\mu}} \right) = g_{\rho\mu} \ddot{x}^{\rho} + \dot{x}^{\rho} \dot{x}^{\nu} \partial_{\nu} g_{\rho\mu} = g_{\rho\mu} \ddot{x}^{\rho} + \frac{1}{2} \left(\dot{x}^{\rho} \dot{x}^{\nu} \partial_{\nu} g_{\rho\mu} + \dot{x}^{\nu} \dot{x}^{\rho} \partial_{\rho} g_{\nu\mu} \right) (4)$$

Thus the Euler-Lagrange equations become

$$\left[\text{E.-L.} \right] = g_{\mu\rho} \ddot{x}^{\rho} + \frac{1}{2} \left(\partial_{\nu} g_{\rho\mu} + \partial_{\rho} g_{\nu\mu} - \partial_{\mu} g_{\rho\nu} \right) \dot{x}^{\nu} \dot{x}^{\rho}$$
(5)

$$= g_{\mu\rho}\ddot{x}^{\rho} + \Gamma_{\mu\nu\rho}\dot{x}^{\rho}\dot{x}^{\nu} = 0$$
(6)

and they can be written in the usual (geodesic equation) form by multiplying by $g^{\lambda\mu}$ to move the index μ up :

$$g^{\lambda\mu}\left(g_{\mu\rho}\ddot{x}^{\rho}+\Gamma_{\mu\nu\rho}\dot{x}^{\rho}\dot{x}^{\nu}\right)=\ddot{x}^{\lambda}+\Gamma^{\lambda}_{\nu\rho}\dot{x}^{\rho}\dot{x}^{\nu}=0$$
(7)

(b) First we compute :

$$\frac{d}{d\tau}\mathcal{L} = \frac{1}{2}\frac{d}{d\tau}g_{\mu\nu}\dot{x}^{\mu}\dot{x}^{\nu} = \frac{1}{2}\left(2g_{\mu\nu}\ddot{x}^{\mu}\dot{x}^{\nu} + (\dot{x}^{\rho}\partial_{\rho}g_{\mu\nu})\dot{x}^{\mu}\dot{x}^{\nu}\right)$$
(8)

Now using the identity

$$\partial_{\rho}g_{\mu\nu} = \Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho} \tag{9}$$

together with the fact that $x^{\mu}(\tau)$ is a solution to the geodesic equation, which means that we also have :

$$\ddot{x}^{\mu} = -\Gamma^{\mu}_{\nu\rho} \dot{x}^{\nu} \dot{x}^{\rho} \tag{10}$$

leaves us with

$$\frac{d}{d\tau}\mathcal{L} = \frac{1}{2} \left(-2g_{\mu\nu}\Gamma^{\mu}_{\lambda\rho}\dot{x}^{\lambda}\dot{x}^{\rho}\dot{x}^{\nu} + \dot{x}^{\rho}(\Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho})\dot{x}^{\mu}\dot{x}^{\nu} \right)$$
(11)

$$= \frac{1}{2} \left(-2\Gamma_{\nu\lambda\rho} \dot{x}^{\lambda} \dot{x}^{\rho} \dot{x}^{\nu} + (\Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho}) \dot{x}^{\mu} \dot{x}^{\nu} \dot{x}^{\rho} \right) = 0 \qquad (12)$$

which is obviously zero if we relabel the indices.

(c) The metric on the 2-sphere is

$$ds^{2} = R^{2} \left(d\theta^{2} + \sin^{2}(\theta) d\phi^{2} \right)$$
(13)

so that in the (θ, ϕ) coordinates we have :

$$g_{\mu\nu} = R^2 \begin{pmatrix} 1 & 0 \\ 0 & \sin(\theta)^2 \end{pmatrix}$$
 $g^{\mu\nu} = R^{-2} \begin{pmatrix} 1 & 0 \\ 0 & \sin(\theta)^{-2} \end{pmatrix}$ (14)

Because $g_{\mu\nu}$ is diagonal and $g_{\mu\nu} = g_{\mu\nu}(\theta)$, the only non-vanishing contributions to the Christoffel symbols will come from terms involving $\partial_{\theta}g_{\phi\phi}$. Keeping this in mind, we first compute the Christoffel symbols with upper index θ ,

$$\Gamma^{\theta}_{\nu\lambda} = \frac{1}{2}g^{\theta\theta}\left(\partial_{\lambda}g_{\theta\nu} + \partial_{\nu}g_{\theta\lambda} - \partial_{\theta}g_{\nu\lambda}\right) = -\frac{1}{2}g^{\theta\theta}\partial_{\theta}g_{\nu\lambda} \tag{15}$$

and we see that the only non-vanishing term with θ on the top is $\Gamma^{\theta}_{\phi\phi}$:

$$\Gamma^{\theta}_{\phi\phi} = -\frac{1}{2}g^{\theta\theta}\partial_{\theta}g_{\phi\phi} = -\sin(\theta)\cos(\theta)$$
(16)

Now if we choose ϕ to be on the top, we get

$$\Gamma^{\phi}_{\nu\lambda} = \frac{1}{2} g^{\phi\phi} \left(\partial_{\lambda} g_{\phi\nu} + \partial_{\nu} g_{\phi\lambda} - \partial_{\phi} g_{\nu\lambda} \right) = \frac{1}{2} g^{\phi\phi} \left(\partial_{\lambda} g_{\phi\nu} + \partial_{\nu} g_{\phi\lambda} \right)$$
(17)

so that the only non-vanishing terms with ϕ on the top are $\Gamma^{\phi}_{\phi\theta} = \Gamma^{\phi}_{\theta\phi}$:

$$\Gamma^{\phi}_{\phi\theta} = \frac{1}{2} g^{\phi\phi} \partial_{\theta} g_{\phi\phi} = \frac{\cos(\theta)}{\sin(\theta)}$$
(18)

With these Christoffel symbols we can now write down the geodesic equation $\ddot{x}^{\mu} + \Gamma^{\mu}_{\nu\rho} \dot{x}^{\nu} \dot{x}^{\rho}$ in the (θ, ϕ) coordinate. We find

$$\begin{aligned}
\ddot{\theta} + \Gamma^{\theta}_{\phi\phi}\dot{\phi}\dot{\phi} &= \ddot{\theta} - \sin(\theta)\cos(\theta)\dot{\phi}\dot{\phi} = 0 \qquad \mu = \theta \\
\ddot{\phi} + 2\Gamma^{\phi}_{\theta\phi}\dot{\theta}\dot{\phi} &= \ddot{\phi} + 2\frac{\cos(\theta)}{\sin(\theta)}\dot{\theta}\dot{\phi} = 0 \qquad \mu = \phi
\end{aligned}$$
(19)

Using the Euler-Lagrange equations with $\mathcal{L} = \frac{1}{2}(\dot{\theta}^2 + \sin(\theta)^2 \dot{\phi}^2)$, we get :

$$\begin{cases} \frac{d}{d\tau} \frac{\partial \mathcal{L}}{\partial \dot{\theta}} - \frac{\partial \mathcal{L}}{\partial \theta} = \frac{1}{2} \left(\frac{d}{d\tau} 2\dot{\theta} - 2\sin(\theta)\cos(\theta)\dot{\phi}^2 \right) = 0\\ \frac{d}{d\tau} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} - \frac{\partial \mathcal{L}}{\partial \phi} = \frac{1}{2} \frac{d}{d\tau} \left(2\sin(\theta)^2 \dot{\phi} \right) = \sin(\theta)^2 \ddot{\phi} + 2\cos(\theta)\sin(\theta)\dot{\theta}\dot{\phi} = 0 \end{cases}$$
(20)

which are the same equations as in (19).

We can easily see that the great circles $(\theta(\tau), \phi(\tau)) = (\tau, \phi_0)$ on S^2 are solutions to the equations just found. It is indeed the case because for that particular solution ϕ is constant along a great circle, which implies $\ddot{\phi} = \dot{\phi} = 0$ and simultaneously $\theta(\tau) = \tau$ so that $\ddot{\theta}$ vanishes. By looking at equation (19) or (20) we can see that every curve with $\ddot{\theta} = \ddot{\phi} = \dot{\phi} = 0$ trivially satisfy both equations and therefore such curves are geodesics.