

## SOLUTIONS TO ASSIGNMENTS 05

1. We first compute the variation of  $\mathcal{E}[\phi] = \frac{1}{2} \int d^3x \left( \vec{\nabla} \phi \right)^2$  :

$$\begin{aligned}
 \delta \mathcal{E}[\phi] &= \int d^3x \vec{\nabla} \phi \cdot \vec{\nabla} \delta \phi \\
 &= \int d^3x \vec{\nabla} \cdot \left( \vec{\nabla} \phi \delta \phi \right) - \int d^3x (\Delta \phi) \delta \phi \\
 &= - \int d^3x (\Delta \phi) \delta \phi ,
 \end{aligned} \tag{1}$$

where the first term in the second line vanishes because it is a boundary term and the variation is zero on the boundary. Finally, because for an extremum the variation has to vanish for any variation  $\delta \phi$ , we conclude

$$\delta \mathcal{E}[\phi] = 0 \quad \forall \delta \phi \quad \Leftrightarrow \quad \Delta \phi = 0 . \tag{2}$$

2. Again we compute the variation in exactly the same way

$$\begin{aligned}
 \delta S[\Phi_a] &= \int d^4x \left[ -\eta^{\alpha\beta} \partial_\alpha \Phi^a \partial_\beta \delta \Phi^b \delta_{ab} - \frac{\partial V}{\partial \Phi^b} \delta \Phi^b \right] \\
 &= \int d^4x \left[ \delta_{ab} \square \Phi^a - \frac{\partial V}{\partial \Phi^b} \right] \delta \Phi^b ,
 \end{aligned} \tag{3}$$

such that we can read off the equations of motion for the fields

$$\square \Phi_b = \frac{\partial V}{\partial \Phi^b} , \tag{4}$$

where  $\Phi_b = \delta_{ab} \Phi^a \equiv \Phi^b$ .

3. It is useful to first recall how this works in the case of classical mechanics (i.e. a 0+1 dimensional “field theory”). Consider a Lagrangian  $L(q, \dot{q}; t)$  that is a total time-derivative, i.e.

$$L(q, \dot{q}; t) = \frac{d}{dt} F(q; t) = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial q(t)} \dot{q}(t) . \tag{5}$$

Then one has

$$\frac{\partial L}{\partial q(t)} = \frac{\partial^2 F}{\partial q(t) \partial t} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t) \tag{6}$$

and

$$\frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial F}{\partial q(t)} \quad \Rightarrow \quad \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial^2 F}{\partial t \partial q(t)} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t) \tag{7}$$

Therefore one has

$$\frac{\partial L}{\partial q(t)} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} \quad \text{identically} \tag{8}$$

Now we consider the field theory case. We define

$$\begin{aligned} L := \frac{d}{dx^\alpha} W^\alpha(\phi; x) &= \frac{\partial W^\alpha}{\partial x^\alpha} + \frac{\partial W^\alpha}{\partial \phi(x)} \frac{\partial \phi(x)}{\partial x^\alpha} \\ &= \partial_\alpha W^\alpha + \partial_\phi W^\alpha \partial_\alpha \phi \end{aligned} \quad (9)$$

to compute the Euler-Lagrange equations for it. One gets

$$\begin{aligned} \frac{\partial L}{\partial \phi} &= \partial_\phi \partial_\alpha W^\alpha + \partial_\phi^2 W^\alpha \partial_\alpha \phi \\ \frac{d}{dx^\beta} \frac{\partial L}{\partial (\partial_\beta \phi)} &= \frac{d}{dx^\beta} \left( \partial_\phi W^\alpha \delta_\alpha^\beta \right) \\ &= \partial_\beta \partial_\phi W^\beta + \partial_\phi^2 W^\beta \partial_\beta \phi, \end{aligned} \quad (10) \quad (11)$$

and realizing that  $\partial_\beta \partial_\phi W^\beta = \partial_\phi \partial_\beta W^\beta$  we have (10) = (11), thus the Euler-Lagrange equations are trivially satisfied.

**Remark:** One can also show the converse: if a Lagrangian  $L$  gives rise to Euler-Lagrange equations that are identically satisfied then (locally) the Lagrangian is a total derivative. The proof is simple. Assume that  $L(q, \dot{q}; t)$  satisfies

$$\frac{\partial L}{\partial q} \equiv \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \quad (12)$$

identically. The left-hand side does evidently not depend on the acceleration  $\ddot{q}$ . The right-hand side, on the other hand, will in general depend on  $\ddot{q}$  - unless  $L$  is at most linear in  $\dot{q}$ . Thus a necessary condition for  $L$  to give rise to identically satisfied Euler-Lagrange equations is that it is of the form

$$L(q, \dot{q}; t) = L^0(q; t) + L^1(q; t) \dot{q} . \quad (13)$$

Therefore

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} = \frac{d}{dt} L^1 = \frac{\partial L^1}{\partial t} + \frac{\partial L^1}{\partial q} \dot{q} \quad (14)$$

and

$$\frac{\partial L}{\partial q} = \frac{\partial L^0}{\partial q} + \frac{\partial L^1}{\partial q} \dot{q} . \quad (15)$$

Noting that the 2nd terms of the previous two equations are equal, the Euler-Lagrange equations thus reduce to the condition

$$\frac{\partial L^1}{\partial t} = \frac{\partial L^0}{\partial q} . \quad (16)$$

This means that locally there is a function  $F(q; t)$  such that

$$L^0 = \partial_t F , \quad L^1 = \partial_q F , \quad (17)$$

and therefore

$$L = L^0 + L^1 \dot{q} = \partial_t F + \partial_q F \dot{q} = \frac{d}{dt} F , \quad (18)$$

as was to be shown. (Proof in the field theory case is analogous)