## Solutions to Assignments 05

1. We first compute the variation of  $\mathcal{E}[\phi] = \frac{1}{2} \int d^3x \, \left(\vec{\nabla}\phi\right)^2$ :

$$\begin{split} \delta \mathcal{E}[\phi] &= \int d^3 x \, \vec{\nabla} \phi \cdot \vec{\nabla} \delta \phi \\ &= \int d^3 x \, \vec{\nabla} \cdot \left( \vec{\nabla} \phi \delta \phi \right) - \int d^3 x \, \left( \Delta \phi \right) \delta \phi \\ &= -\int d^3 x \, \left( \Delta \phi \right) \delta \phi \,, \end{split} \tag{1}$$

where the first term in the second line vanishes because it is a boundary term and the variation is zero on the boundary. Finally, because for an extremum the variation has to vanish for any variation  $\delta\phi$ , we conclude

$$\delta \mathcal{E}[\phi] = 0 \ \forall \ \delta \phi \ \Leftrightarrow \ \Delta \phi = 0 \ . \tag{2}$$

2. Again we compute the variation in exactly the same way

$$\delta S[\Phi_a] = \int d^4x \left[ -\eta^{\alpha\beta} \partial_\alpha \Phi^a \partial_\beta \delta \Phi^b \delta_{ab} - \frac{\partial V}{\partial \Phi^b} \delta \Phi^b \right] \\ = \int d^4x \left[ \delta_{ab} \Box \Phi^a - \frac{\partial V}{\partial \Phi^b} \right] \delta \Phi^b , \qquad (3)$$

such that we can read off the equations of motion for the fields

$$\Box \Phi_b = \frac{\partial V}{\partial \Phi^b} \,, \tag{4}$$

where  $\Phi_b = \delta_{ab} \Phi^a \equiv \Phi^b$ .

3. It is useful to first recall how this works in the case of classical mechanics (i.e. a 0+1 dimensional "field theory"). Consider a Lagrangian  $L(q, \dot{q}; t)$  that is a total time-derivative, i.e.

$$L(q, \dot{q}; t) = \frac{d}{dt} F(q; t) = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial q(t)} \dot{q}(t) \quad .$$
(5)

Then one has

$$\frac{\partial L}{\partial q(t)} = \frac{\partial^2 F}{\partial q(t)\partial t} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t) \tag{6}$$

and

$$\frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial F}{\partial q(t)} \quad \Rightarrow \quad \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial^2 F}{\partial t \partial q(t)} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t) \tag{7}$$

Therefore one has

$$\frac{\partial L}{\partial q(t)} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} \qquad \text{identically} \tag{8}$$

Now we consider the field theory case. We define

$$L := \frac{d}{dx^{\alpha}} W^{\alpha}(\phi; x) = \frac{\partial W^{\alpha}}{\partial x^{\alpha}} + \frac{\partial W^{\alpha}}{\partial \phi(x)} \frac{\partial \phi(x)}{\partial x^{\alpha}}$$
$$= \partial_{\alpha} W^{\alpha} + \partial_{\phi} W^{\alpha} \partial_{\alpha} \phi \tag{9}$$

to compute the Euler-Lagrange equations for it. One gets

$$\frac{\partial L}{\partial \phi} = \partial_{\phi} \partial_{\alpha} W^{\alpha} + \partial_{\phi}^{2} W^{\alpha} \partial_{\alpha} \phi \qquad (10)$$

$$\frac{d}{dx^{\beta}} \frac{\partial L}{\partial(\partial_{\beta}\phi)} = \frac{d}{dx^{\beta}} \left( \partial_{\phi} W^{\alpha} \delta^{\beta}_{\alpha} \right)$$

$$= \partial_{\beta} \partial_{\phi} W^{\beta} + \partial_{\phi}^{2} W^{\beta} \partial_{\beta} \phi , \qquad (11)$$

and realizing that  $\partial_{\beta}\partial_{\phi}W^{\beta} = \partial_{\phi}\partial_{\beta}W^{\beta}$  we have (10) = (11), thus the Euler-Lagrange equations are trivially satisfied.

**Remark:** One can also show the converse: if a Lagrangian L gives rise to Euler-Lagrange equations that are identically satisfied then (locally) the Lagrangian is a total derivative. The proof is simple. Assume that  $L(q, \dot{q}; t)$  satisfies

$$\frac{\partial L}{\partial q} \equiv \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \tag{12}$$

identically. The left-hand side does evidently not depend on the acceleration  $\ddot{q}$ . The right-hand side, on the other hand, will in general depend on  $\ddot{q}$  - unless L is at most linear in  $\dot{q}$ . Thus a necessary condition for L to give rise to identically satisfied Euler-Lagrange equations is that it is of the form

$$L(q, \dot{q}; t) = L^{0}(q; t) + L^{1}(q; t)\dot{q} \quad .$$
(13)

Therefore

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}} = \frac{d}{dt}L^1 = \frac{\partial L^1}{\partial t} + \frac{\partial L^1}{\partial q}\dot{q}$$
(14)

and

$$\frac{\partial L}{\partial q} = \frac{\partial L^0}{\partial q} + \frac{\partial L^1}{\partial q} \dot{q} \quad . \tag{15}$$

Noting that the 2nd terms of the previous two equations are equal, the Euler-Lagrange equations thus reduce to the condition

$$\frac{\partial L^1}{\partial t} = \frac{\partial L^0}{\partial q} \quad . \tag{16}$$

This means that locally there is a function F(q;t) such that

$$L^0 = \partial_t F \quad , \quad L^1 = \partial_q F \quad , \tag{17}$$

and therefore

$$L = L^0 + L^1 \dot{q} = \partial_t F + \partial_q F \dot{q} = \frac{d}{dt} F \quad , \tag{18}$$

as was to be shown. (Proof in the field theory case is analogous)