Solutions to Assignments 05

1. It is useful to first recall how this works in the case of classical mechanics (i.e. a 0+1 dimensional "field theory"). Consider a Lagrangian $L(q, \dot{q}; t)$ that is a total time-derivative, i.e.

$$L(q, \dot{q}; t) = \frac{d}{dt} F(q; t) = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial q(t)} \dot{q}(t) \quad .$$
(1)

Then one has

$$\frac{\partial L}{\partial q(t)} = \frac{\partial^2 F}{\partial q(t)\partial t} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t)$$
(2)

and

$$\frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial F}{\partial q(t)} \quad \Rightarrow \quad \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} = \frac{\partial^2 F}{\partial t \partial q(t)} + \frac{\partial^2 F}{\partial q(t)^2} \dot{q}(t) \tag{3}$$

Therefore one has

$$\frac{\partial L}{\partial q(t)} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}(t)} \qquad \text{identically} \tag{4}$$

Now we consider the field theory case. We define

$$L := \frac{d}{dx^{a}}W^{a}(\phi; x) = \frac{\partial W^{a}}{\partial x^{a}} + \frac{\partial W^{a}}{\partial \phi(x)}\frac{\partial \phi(x)}{\partial x^{a}}$$
$$= \partial_{a}W^{a} + \partial_{\phi}W^{a}\partial_{a}\phi$$
(5)

to compute the Euler-Lagrange equations for it. One gets

$$\frac{\partial L}{\partial \phi} = \partial_{\phi} \partial_a W^a + \partial_{\phi}^2 W^a \partial_a \phi \tag{6}$$

$$\frac{d}{dx^{b}}\frac{\partial L}{\partial(\partial_{b}\phi)} = \frac{d}{dx^{b}}\left(\partial_{\phi}W^{a}\delta_{a}^{b}\right)$$

$$= \partial_{b}\partial_{\phi}W^{b} + \partial_{\phi}^{2}W^{b}\partial_{b}\phi .$$
(7)

Thus (since partial derivatives commute) the Euler-Lagrange equations are satisfied identically.

Remark: One can also show the converse: if a Lagrangian L gives rise to Euler-Lagrange equations that are identically satisfied then (locally) the Lagrangian is a total derivative. The proof is simple. Assume that $L(q, \dot{q}; t)$ satisfies

$$\frac{\partial L}{\partial q} \equiv \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \tag{8}$$

identically. The left-hand side does evidently not depend on the acceleration \ddot{q} . The right-hand side, on the other hand, will in general depend on \ddot{q} - unless L is at most linear in \dot{q} . Thus a necessary condition for L to give rise to identically satisfied Euler-Lagrange equations is that it is of the form

$$L(q, \dot{q}; t) = L^{0}(q; t) + L^{1}(q; t)\dot{q} \quad .$$
(9)

Therefore

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{q}} = \frac{d}{dt}L^1 = \frac{\partial L^1}{\partial t} + \frac{\partial L^1}{\partial q}\dot{q}$$
(10)

and

$$\frac{\partial L}{\partial q} = \frac{\partial L^0}{\partial q} + \frac{\partial L^1}{\partial q}\dot{q} \quad . \tag{11}$$

Noting that the 2nd terms of the previous two equations are equal, the Euler-Lagrange equations thus reduce to the condition

$$\frac{\partial L^1}{\partial t} = \frac{\partial L^0}{\partial q} \quad . \tag{12}$$

This means that locally there is a function F(q;t) such that

$$L^0 = \partial_t F \quad , \quad L^1 = \partial_q F \quad , \tag{13}$$

and therefore

$$L = L^0 + L^1 \dot{q} = \partial_t F + \partial_q F \dot{q} = \frac{d}{dt} F \quad , \tag{14}$$

as was to be shown. (Proof in the field theory case is analogous)

2. Complex Scalar Field I: Action and Equations of Motion

The action is

$$S[\Phi] = \int d^4x \left(-\frac{1}{2} \eta^{ab} \partial_a \Phi \partial_b \Phi^* - W(\Phi, \Phi^*) \right)$$

=
$$\int d^4x \left(-\frac{1}{2} \eta^{ab} \partial_a \phi_1 \partial_b \phi_1 - \frac{1}{2} \eta^{ab} \partial_a \phi_2 \partial_b \phi_2 - V(\phi_1, \phi_2) \right)$$
(15)

(a) Varying ϕ_1 in the 2nd line, while keeping ϕ_2 fixed, one finds

$$\delta S = \int d^4x \left(-\eta^{ab} \partial_a \phi_1 \partial_b \delta \phi_1 - (\partial V/\partial \phi_1) \delta \phi_1 \right) \quad . \tag{16}$$

Integrating by parts the first term, and dropping the boundary term, one finds the Euler-Lagrange equation $\Box \phi_1 = \partial V / \partial \phi_1$. Analogous for ϕ_2 .

(b) Using

$$\frac{\partial V}{\partial \phi_1} = (\frac{\partial W}{\partial \Phi})(\frac{\partial \Phi}{\partial \phi_1}) + (\frac{\partial W}{\partial \Phi^*})(\frac{\partial \Phi^*}{\partial \phi_1}) = (\frac{\partial W}{\partial \Phi}) + (\frac{\partial W}{\partial \Phi^*})(\frac{\partial \Phi^*}{\partial \phi_2}) = i(\frac{\partial W}{\partial \Phi}) - i(\frac{\partial W}{\partial \Phi^*})(\frac{\partial \Phi^*}{\partial \phi_2}) = i(\frac{\partial W}{\partial \Phi}) - i(\frac{\partial W}{\partial \Phi^*})(\frac{\partial \Phi^*}{\partial \Phi^*})$$
(17)

one finds

$$\Box \Phi = \Box \phi_1 + i \Box \phi_2 = \partial V / \partial \phi_1 + i \partial V / \partial \phi_2 = 2 \partial W / \partial \Phi^*$$

$$\Box \Phi^* = \Box \phi_1 - i \Box \phi_2 = \partial V / \partial \phi_1 - i \partial V / \partial \phi_2 = 2 \partial W / \partial \Phi$$
 (18)

(c) Varying only Φ^* in the first line of the action, while keeping Φ fixed, one finds

$$\delta S = \int d^4x \left(-\frac{1}{2} \eta^{ab} \partial_a \Phi \partial_b \delta \Phi^* - (\partial W / \partial \Phi^*) \delta \Phi^* \right) \quad . \tag{19}$$

Integrating by parts the 1st term, one obtains $(1/2)\Box\Phi$, and thus the correct Euler-Lagrange equation for Φ (analogously for $\Phi \leftrightarrow \Phi^*$).